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Метод контроля усилия натяжения металлотрикотажного сетеполотна на крупногабаритных рефлекторах антенн

Е. А. Грачева, Ф. К. Синьковский

АО «Информационные спутниковые системы» имени академика М. Ф. Решетнёва» (АО «РЕШЕТНЁВ») Российская Федерация, 662970, г. Железногорск Красноярского края, ул. Ленина, 52 *E-mail:grachevaea@iss-reshetnev.ru

Приведены некоторые основные параметры сетеполотна, влияющие на радиоотражающие свойства рефлектора, и технология достижения этих параметров с помощью контроля усилия натяжения сетеполотна на различных этапах изготовления радиоотражающей поверхности рефлектора. Сделан краткий обзор существующих и применяемых на предприятии АО «РЕШЕТНЁВ» методов измерения и контроля усилия натяжения сетеполотна рефлекторов космических аппаратов и представлен анализ недостатков в результате их отработки. Предложен новый метод контроля усилия натяжения, основанный на локальном деформировании сетеполотна силой давления втягиваемого воздуха через его поверхность. Представлены результаты разработки и испытаний метода и прототипа устройства для контроля усилия натяжения сетеполотна. Целью исследования являлось определение работоспособности устройства и возможности его дальнейшего применения для контроля натяжения сетеполотна на рабочих рефлекторах.

Разработанный метод и прототип устройства, его реализующего, позволяют оперативно проводить контроль усилия натяжения сетеполотна при любом его пространственном положении.

Предложены и проанализированы перспективы возможного использования метода в ракетнокосмической промышленности при изготовлении радиоотражающих поверхностей антенн космических аппаратов. По результатам проведенного исследования установлена зависимость усилия натяжения сетеполотна от силы давления втягиваемого воздуха через сетеполотно. Выявлена необходимость в дальнейшей доработке разработанного устройства для повышения точности получения данных измерений.

При успешном испытании доработанного устройства контроля усилия натяжения сетеполотна в лабораторных условиях, будут проведены дальнейшие испытания на стадии раскроя сетеполотна и на сетеполотне в составе рефлектора.

Ключевые слова: рефлектор, радиоотражающая поверхность, металлическое сетеполотно, усилие натяжения сетеполотна, коэффициент отражения.

Research of a method based on the local deformation of the metall mesh by the force of air drawn through its surface, for measuring and controlling the tension force of the metall mesh cavity on radio-reflecting reflectors

E. A. Gracheva, F. K. Sin'kovskiy

JSC Academician M. F. Reshetnev "Information Satellite Systems" (RESHETNEV JSC) 52, Lenin St., Zheleznogorsk, Krasnoyarsk region, 662972, Russian Federation E-mail:grachevaea@iss-reshetnev.ru

This article presents some of the main parameters of metal mesh that affect the radio-reflective properties of reflectors and the technology for attaining these parameters by controlling the tension capacity of the mesh sheet at various stages of the radio-reflective surface manufacturing. The article also includes a brief overview of the developed methods (applied at the RESHETNEV JSC) of measuring and controlling the tension capacity of spacecraft reflectors with mesh shields, along with the analysis of the shortcomings revealed in the application of these methods. The authors introduce a new method of the tension capacity control based on the local deformation of the metal mesh by pressure of the air drawn through its surface. There are the results of development and testing of the metod, and of a model device for controlling the mesh tension capacity. The purpose of the research is to determine the operability of the device and the ways of its possible application in controlling the tension of the mesh-made reflectors ready for operation.

The developed method and the model device for its application allow in-process control of the mesh tension at any spatial position of the mesh sheet.

There is an analysis of possible application prospects of the method in rocket and space industry for manufacturing radio-reflecting surfaces of spacecraft antennas. According to the results of the research, the ratio of the mesh tension capacity to the pressure of the air drawn through the sheet was determined. The need for further improvement of the designed device aimed at increasing the measurement data accuracy was also pointed out.

In case the laboratory testing of the upgraded device for controlling the mesh tension capacity proves successful, further tests will be carried out in the process of sheet cutting and in the reflector shield manufacture.

Keywords: reflector, radio-reflective surface, metal mesh, mesh tension capacity, reflection coefficient.

Introduction

Desingn of fundamentally new transformable antennas for spacecraft required the development of metal mesh products, tactical and technical characteristics of which could ensure the highest reflection coefficient of microwave radiation at minimal tension force, minimum specific weight and maximum isotropy of mechanical and radio engineering properties [1–3].

The reflective surface of space communication antennas is subject to specific operational requirements, one of which is maximum radio-reflecting capacity at minimal tension of the load-bearing frame [4].

The problem of reflective surface manufacture was solved through the development of new woven metal mesh materials made of galvanically gilded wire, which best meet the present requirements for a reflection coefficient of ≥ 98 %.

The required antenna reflection coefficient depends, among other parameters, on the amount and uniformity of the mesh sheet tension over the entire diameter of the operating reflector aperture.

The article gives a review of the methods applied at the RESHETNYOV JSC for measuring and control of the mesh tension value when dealing with large-size transformable antenna reflectors; there is also a presentation of a new control method.

Formation and control of the surface profile of radio reflectors

Tungsten and molybdenum mesh with gold coating is used as the material for the radio-reflective surfaces of large-size reflectors.

To maintain the specified coefficient of radio reflection in the process of antenna deployment, the radio-reflecting surface of the corresponding profile must be supplied [5; 6].

When the profile able to eliminate sagging of the mesh shield framed by power spokes is manufactured, the mesh must have the tension determined at the JSC RESHETNYOV – conducted test session (the figures obtained see in Table 1).

Table 1

Mesh grade	Mesh tension capacity, g/cm
CMeT-3лB15x2(A+A)	5 ± 1
СМеТ-3лB15x2(T+C)	11 ± 1
CMeT-3лMo20x1(A+A)	2 ± 1

The value of operational mesh tension capacity for various mesh sheet grades

Control of the mesh tension capacity is specified in the design documentation for transformable reflectors and metal mesh [7; 8]:

- at the stage of mesh sheet cutting;

- at the dimensional template, when the mesh sheet is lined out;

- at various production stages of the reflector.

The number of control points depends on the diameter of the antenna and ranges from several tens to several hundreds.

Analysis of methods of tension capacity measurement and control maintaining the antenna radio-reflective parameters

At present, the JSC "RESHETNYOV" makes use of the following developed and industrially applied methods of mesh tension measurement and control:

- a method of tension capacity control based on the density of loops in the mesh, that is, on counting loops on digital photographs at any stage of the mesh fabrication [9–12];

- a method of tension capacity control by measuring the mesh sheet deflection when a certain pressure is applied to its surface [13–15].

The resonance method was also proposed and investigated. The method bases on exposing the mesh to the effect of sound waves of various frequency until the frequency of the wave from the external source equals the natural frequency of the sheet's free vibrations, which causes resonance. Thus, depending on the mesh tension capacity, the natural frequency of free vibrations also changes; this changes the resonant peaks arising at coincidence with the frequency of sound waves from the external source. The moments of resonant peaks were registered by sensors distributed over the mesh sheet, then the obtained values were displayed on a multimeter (measurements given in millivolts) - these proved proportional to the tension effort applied to the mesh [16].

The analysis of the methods' application showed that the device for measuring the deflection of the mesh sheet allows monitoring only on the mesh-cutting platform, and is not suitable for the parametrical control of the sheet as part of the reflector.

The method of tension capacity control by measuring the density of loops in the mesh does not provide the required control accuracy. The main reason is the need to keep the photocamera lens perpendicular to the surface of the mesh, which is not possible due to the spherical setting of the mesh as part of the reflector. Moreover, the method does not provide operational responsiveness in measurements. The method applying sound waves is operational only at the stages of mesh cutting or manufacturing limited mesh segments. The method is also not applicable to actual reflectors, as it appears nonproductive in technique.

Method based on the local deformation of the mesh by the pressure of the air drawn through its surface

Considering the shortcomings of the above reviewed methods, a new method of mesh tension capacity control was worked out, a method of the local deformation of the mesh sheet by the pressure of the air drawn through its surface.

The operating principle of the method is in measuring the pressure of the air drawn through the mesh at the moment of the target mesh deflection.

To confirm the efficiency of the method, tests were carried out to assess the effect of the mesh tension capacity on the pressure of the air drawn through the mesh surface until the deflection is caused .

To carry out the tests, a special framework simulating the mesh shield tension on the reflector frame was assembled.

The framework design is shown in Fig. 1. In the course of tests, a mesh fragment (1) measuring 17 x 17 cm was rigidly fixed to a rectangular frame along two perpendicular sides (2). Weights (3) were suspended on the other two free sides at regular intervals, creating a uniform tensile load on the mesh. To assure the accuracy of the tests, a target test area was selected in the center of the fragment (4), as the tension force is most evenly distributed within this area.



Fig. 1. Mesh with evenly distributed load: 1 - mesh; 2 - rigid fastening; 3 - loads; 4 - test area

Рис. 1. Сетеполотно с равномерной распределенной нагрузкой: 1 – сетеполотно; 2 – жесткое крепление; 3 – грузы; 4 – исследуемая область

To test the method, a model device for the tension capacity control was constructed.

The working principle of the device is shown in Fig. 2.

The operation principle of the device is as follows: the fan impeller (1), located inside the inlet pipe (3) and powered by the electric actuator (2) connected to the power source (9) through the fan control unit (7), creates a reverse airflow. The free end of the inlet pipe (3) touches the mesh sheet, and with the potentiometer hand control (8) attached to the fan control unit (7), the drawn air flow can be regulated till the mesh gets deflected (11).



Fig. 2. Design of the device for tension capacity measurement and control:
1 - fan impeller; 2 - electric fan actuator; 3 - inlet pipe (diameter 10 mm); 4 - contacting unit;
5 - digital display; 6 - control LED; 7 - fan control unit; 8 - regulating potentiometer; 9 - power source;
10 - ring-shaped end of the pipe that contacts the mesh; 11 - amount of the mesh deflection

Рис. 2. Схема устройства для контроля усилия натяжения: *1* – крыльчатка вентилятора; 2 – электропривод вентилятора;
3 – впускной патрубок диаметром 10 мм; 4 – контактная группа;
5 – цифровой дисплей; 6 – контрольный светодиод;
7 – блок управления вентилятором; 8 – регулирующий потенциометр;
9 – источник питания; 10 – кольцевой контакт патрубка с полотном;
11 – величина прогиба полотна

As soon as the air flow pressure becomes sufficient, electricity is fed from the contacting unit (4) to the mesh sheet. The moment the feeding starts, the control LED (6) lights up - that signals for taking readings from the digital display (5), which shows the voltage on the regulating potentiometer (8).

The digital display readings are proportional to the force of the drawn airflow acting on the mesh sheet.

This way, five tests with the device were carried out for loads of 0, 50, 100, 150 and 200 g per side of the mesh fragment. In each test, the measurements were taken three times in order to confirm the results and reduce errors.

The ratio of the pressure of the air drawn through the sheet to the mesh tension capacity are given in Table. 2.

Table 2

Nº Tot tst. si	Total load per	Tension force per side (σ) .	Digital display readings, mV			Average value
	side (m), g	g/см	1 msm.	2 msm.	3 msm.	acc.to all measurements, mV
1	0	0	459	460	465	461,3
2	50	2,9	465	465	470	466,6
3	100	5,8	470	471	473	471,3
4	150	8,8	472	476	479	475,6
5	200	11,7	475	479	481	478,3

Ratio of the drawn airflow force to the mesh tension capacity

As the result of the research, the general ratio of the mesh tension capacity to the pressure of the air drawn through the sheet was determined (Fig. 3).



Fig. 3. The ratio of the force of the air drawn through the mesh surface to the tension force applied to the mesh



According to the the graphic chart of the ratio, the greater is the tension applied to the mesh, the greater force of the drawn air is necessary to induce powered contact of the contacting unit and the mesh sheet.

Conclusion

The present research determined the ratio of the tension applied to the mesh to the force of the drawn air the mesh surface is exposed to.

It was stated that, in order to use the method, additional adjustment of the designed device should be carried out before actuall operation. In this regard, the tension capacity control device should be calibrated and checked on a reference mesh fragment for each mesh grade. Accordingly, a calibration table should be drawn up, showing how the mesh tension capacity is reflected by the digital indicator readings for each value of the applied tension.

The method needs additional research and improvement in order to increase the accuracy of the model device readings; the construction of the device should also be made simpler. However, the device demonstrates obvious prospects of its further industrial application, as, unlike other methods, it allows taking measurements of the mesh tension capacity on a spherical surface, displaying in the process correct digital values.

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Грачева Евгения Александровна – инженер, Акционерное общество «Информационные спутниковые системы имени академика М. Ф. Решетнева»; аспирант, Сибирский государственный университет науки и технологий имени академика М. Ф. Решетнева. E-mail: grachevaea@iss-reshetnev.ru.

Синьковский Федор Константинович – заместитель директора – главный конструктор отраслевого центра крупногабаритных трансформируемых механических систем; Акционерное общество «Информационные спутниковые системы имени академика М. Ф. Решетнева». Е-mail: sfk@iss-reshetnev.ru.

Gracheva Evgeniya Aleksandrovna – Engineer, Joint-Stock Company "Information Satellite systems named after Academician M. F. Reshetnev"; postgraduate student, Reshetnev Siberian State University of Science and Technology. E-mail: grachevaea@iss-reshetnev.ru.

Sin'kovskiy Fedor Konstantinovich – Deputy Director-Chief Designer of the industry center for large-size transformable mechanical systems; Joint-Stock Company "Information Satellite systems named after Academician M. F. Reshetnev". E-mail: sfk@iss-reshetnev.ru.